

# International Journal of Scientific Development and Research

IJSDR.ORG | ISSN : 2455-2631



*An International Open Access, Peer-reviewed, Refereed Journal*

The Board of  
International Journal of Scientific Development and Research  
Is hereby awarding certificate to  
**Er. Pragati Pal**

In recognition of the publication of the paper entitled  
**Object Tracking Mobile Robot With Visual Feedback and Zigbee**  
Published in Volume 2 Issue 5, April-2017, | Impact Factor: 9.15 by Google Scholar

Co-Authors - Pandey Ajitkumar Rajendra, Shaikh Iqra Rashid Ali, Shukla Ankur Rakesh

Paper ID - IJSDR1705005  
Registration ID - 170338



  
Editor-in-Chief

An International Scholarly, Open Access, Multi-disciplinary, Monthly, Indexing in all Major Database & Metadata, Citation Generator

**IJSDR - International Journal of Scientific Development and Research | ESTD: 2016**

[www.ijedr.org](http://www.ijedr.org) | [editor@ijedr.org](mailto:editor@ijedr.org)

Certificate of Publication

IJSDR | ISSN : 2455-2631

# International Journal of Scientific Development and Research

IJSDR.ORG | ISSN : 2455-2631



*An International Open Access, Peer-reviewed, Refereed Journal*

The Board of  
International Journal of Scientific Development and Research

Is hereby awarding certificate to

**Pandey Ajitkumar Rajendra**

In recognition of the publication of the paper entitled

**Object Tracking Mobile Robot With Visual Feedback and Zigbee**

Published in Volume 2 Issue 5, April-2017, | Impact Factor: 9.15 by Google Scholar

Co-Authors - Er. Pragati Pal, Shaikh Iqra Rashid Ali, Shukla Ankur Rakesh



Paper ID - IJSDR1705005  
Registration ID - 170338

  
Editor-in-Chief

An International Scholarly, Open Access, Multi-disciplinary, Monthly, Indexing in all Major Database & Metadata, Citation Generator

**IJSDR - International Journal of Scientific Development and Research | ESTD: 2016**

[www.ijedr.org](http://www.ijedr.org) | [editor@ijedr.org](mailto:editor@ijedr.org)

Certificate of Publication

IJSDR | ISSN : 2455-2631

# International Journal of Scientific Development and Research

IJSDR.ORG | ISSN : 2455-2631



*An International Open Access, Peer-reviewed, Refereed Journal*

The Board of  
International Journal of Scientific Development and Research

Is hereby awarding certificate to

**Shaikh Iqra Rashid Ali**

In recognition of the publication of the paper entitled

**Object Tracking Mobile Robot With Visual Feedback and Zigbee**

Published in Volume 2 Issue 5, April-2017, | Impact Factor: 9.15 by Google Scholar

Co-Authors - Er. Pragati Pal, Pandey Ajitkumar Rajendra, Shukla Ankur Rakesh



Paper ID - IJSDR1705005  
Registration ID - 170338

  
Editor-in-Chief

An International Scholarly, Open Access, Multi-disciplinary, Monthly, Indexing in all Major Database & Metadata, Citation Generator

**IJSDR - International Journal of Scientific Development and Research | ESTD: 2016**

[www.ijedr.org](http://www.ijedr.org) | [editor@ijedr.org](mailto:editor@ijedr.org)

Certificate of Publication

IJSDR | ISSN : 2455-2631



# International Journal of Scientific Development and Research

IJSDR.ORG | ISSN : 2455-2631



*An International Open Access, Peer-reviewed, Refereed Journal*

The Board of  
International Journal of Scientific Development and Research

Is hereby awarding certificate to

**Shukla Ankur Rakesh**

In recognition of the publication of the paper entitled

**Object Tracking Mobile Robot With Visual Feedback and Zigbee**

Published in Volume 2 Issue 5, April-2017, | Impact Factor: 9.15 by Google Scholar

Co-Authors - Er. Pragati Pal, Pandey Ajitkumar Rajendra, Shaikh Iqra Rashid Ali



Paper ID - IJSDR1705005  
Registration ID - 170338

  
Editor-in-Chief

An International Scholarly, Open Access, Multi-disciplinary, Monthly, Indexing in all Major Database & Metadata, Citation Generator

**IJSDR - International Journal of Scientific Development and Research | ESTD: 2016**

[www.ijedr.org](http://www.ijedr.org) | [editor@ijedr.org](mailto:editor@ijedr.org)

Certificate of Publication

IJSDR | ISSN : 2455-2631